

## Course Number: 0302101

<u>Course Title:</u> Introductory Physics 1 <u>Prerequisites and/or Corequisites:</u> None

#### Textbook: "University Physics with Modern Physics".

H. D. Young and R. A. Freedman

15<sup>th</sup> edition (Pearson, 2020)

#### Recommended References:

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- 1. R. A. Serway and J. W. Jewett Jr., "Physics for Scientists and Engineers with Modern Physics", 9<sup>th</sup> edition, (Thomson Learning, Belmont, CA, USA, 2014).
- 2. D. Halliday, R. Resnick, and J. Walker, "Extended Principles of Physics", 9<sup>th</sup> Edition (John Wiley & Sons, Inc., 2011).
- 3. W. Bauer, G. D. Westfall, "University Physics with Modern Physics", (McGraw Hill, 2011).
- 4. J. S. Walker, "Physics" Fourth Edition, (Addison Wesley, 2010).
- 5. Giancoli, "Physics for Scientists & Engineers with Modern Physics", Fourth Edition, (Pearson Education, 2009).
- 6. Ohanian and Market, "Physics for Engineers and Scientists", Extended Third Edition, (W. W. Norton & Company, 2007).

#### Course Contents:

| Chapter | Contents   |
|---------|--|
| 1       | Units, Physical Quantities and Vectors 1.7 Vectors and Vector Addition |
|         | <ul><li>1.8 Components of Vectors</li><li>1.9 Unit Vectors</li></ul>   |
|         | 1.10 Products of Vectors   |
| 2       | Motion Along a Straight Line   |
|         | 2.1 Displacement, Time, Average Velocity                               |
|         | 2.2 Instantaneous Velocity   |
|         | 2.3 Average and instantaneous Acceleration                             |
|         | 2.4 Motion with Constant Acceleration                                  |
|         | 2.5 Freely Fulling Objects<br>2.6 Velocity and Position by Integration |
|         | Antion in Two or Three Dimensions                                      |
| 3       | 2.1 Desition and Velocity Vectors                                      |
|         | 3.1 Position und verocity vectors                                      |
|         | 3.3 Projectile Mation  |
|         | 3.4 Motion in a Circle   |
|         | Newton's Laws of Motion  |
|         | 4.1 Force and Interactions   |
|         | 4.2 Newton's First Law   |
| 4       | 4.3 Newton's Second Law  |
|         | 4.4 Mass and Weight  |
|         | 4.5 Newton's Third Law   |
|         | 4.6 Free body Diagrams   |
| 13      | 13.1 Newton's Law of Gravitation                                       |
|         | 13.2 Weight  |
|         | Applying Newton's Laws   |
|         | 5.1 Using Newton's First Law: Particles in Equilibrium                 |
| 5       | 5.2 Using Newton's Second Law: Dynamics of Particles                   |
|         | 5.3 Friction Forces  |
|         | 5.4 Dynamics of Circular Motion  |
|         | 5.5 The Fundamental Forces of Nature                                   |

|    | Work and Kinetic Energy                               |  |  |  |
|----|---|--|--|--|
| 6  | 6.1 Work  |  |  |  |
|    | 6.2 Kinetic Energy and the Work-Energy Theorem        |  |  |  |
|    | 6.3 Work and Energy with Varying Forces               |  |  |  |
|    | 6.4 Power   |  |  |  |
| 7  | Potential Energy and Energy Conservation              |  |  |  |
|    | 7.1 Gravitational Potential Energy                    |  |  |  |
|    | 7.2 Elastic Potential Energy                          |  |  |  |
|    | 7.3 Conservative and Non-Conservative Forces          |  |  |  |
|    | 7.4 Force and Potential Energy                        |  |  |  |
| 8  | Momentum, Impulse, and Collisions                     |  |  |  |
|    | 8.1 Momentum and Impulse                              |  |  |  |
|    | 8.2 Conservation of Momentum                          |  |  |  |
|    | 8.3 Momentum Conservation and Collisions              |  |  |  |
|    | 8.4 Elastic Collisions                                |  |  |  |
|    | 8.5 Centre of Mass (No Integrals)                     |  |  |  |
|    | Rotation of Rigid Bodies                              |  |  |  |
|    | 9.1 Angular Velocity and Acceleration                 |  |  |  |
| 9  | 9.2 Rotation with Constant Angular Acceleration       |  |  |  |
| 5  | 9.3 Relating Linear and Angular Kinematics            |  |  |  |
|    | 9.4 Energy in Rotational Motion                       |  |  |  |
|    | 9.5 Parallel-Axis Theorem                             |  |  |  |
|    | Dynamics of Rotational Motion                         |  |  |  |
|    | 10.1 Torque   |  |  |  |
| 10 | 10.2 Torque and Angular Acceleration for a Rigid Body |  |  |  |
|    | 10.4 Work and Power in Rotational Motion              |  |  |  |
|    | 10.5 Angular Momentum                                 |  |  |  |
|    | 10.6 Conservation of Angular Momentum                 |  |  |  |
| 11 | Equilibrium and Elasticity ( <u>self-reading</u> )    |  |  |  |
|    | 11.1 Conditions for Equilibrium                       |  |  |  |
|    | 11.2 Centre of Gravity                                |  |  |  |
|    | 11.3 Solving Rigid-Body Equilibrium Problems          |  |  |  |

### Course Coordinator:

• Dr. Moneeb Shatnawi E-mail: <u>moneeb.shatnawi@ju.edu.jo</u>

<u>Course web site:</u> Students of all sections of physics 101 are required to frequently check the announcements written at the course e-learning web site: <u>https://elearning.ju.edu.jo/moodle10/course/view.php?id=8553</u>

#### Examinations:

All exams are multiple-choice and computerized.

| Exam   | Weight %    | Tentative Date        | Included Material                                |
|--------|-------------|-----------------------|--|
| First  | 20 %        | To be announced later | Required sections in chapters:<br>1, 2, 3        |
| Second | 30 %        | To be announced later | Required sections in chapters:<br>4, 5, 13, 6, 7 |
| Final  | <b>50 %</b> | To be announced later | Required sections in all chapters.               |

# Good Luck!!!