

Experimental Errors.

* Types of Experimental errors:-

- 1) Personal error :- due to observer carelessness.
- 2) Systematic error :- from the instrument.
- 3) Random error :- accidental error.

Note:-

- Personal, Systematic errors can be controlled
- Random errors beyond your control.

* How to calculate errors?

① Error due to instrument

$$= \frac{\text{smallest division}}{2}$$

② Percentage Error.

For several trials with accepted value

$$= \left| \frac{E - A}{A} \right| \times 100\%$$

③ Percentage difference.

For several trials with out accepted value.

$$= \left| \frac{E_{avg.} - E_{min.}}{\left(\frac{E_{max.} + E_{min.}}{2} \right)} \right| \times 100\% \quad \text{45°}$$

④ Standard mean deviation

for several trials

$$= \sqrt{\frac{\sum (A_n - \bar{A})^2}{n(n-1)}}$$

⑤ Error while calculating values:

(a) addition and subtraction

$$\text{e.g. } A = B + C - D$$

$$\Delta A = \sqrt{\Delta B^2 + \Delta C^2 + \Delta D^2}$$

$$\Rightarrow (A \pm \Delta A)$$

(b) multiplication and division

$$A = \frac{BC}{D}$$

$$\frac{\Delta A}{A} = \sqrt{\left(\frac{\Delta B}{B}\right)^2 + \left(\frac{\Delta C}{C}\right)^2 + \left(\frac{\Delta D}{D}\right)^2}$$

(c) Power

$$A = B^N$$

$$\frac{\Delta A}{A} = N \left(\frac{\Delta B}{B} \right)^*$$

log vs log graph

$$\Rightarrow \log A = m \log d + b$$

$$\Rightarrow A = d^m \cdot 10^b$$

* note * * * $y = mx + b$

Exp 2 Measurements and Uncertainties

1 Pan balance :- used to measure masses
it's smallest division is 0.01 gram

$$\Delta m = \frac{\text{smallest division}}{2} = \pm 0.005$$

2 Meter stick :- it's smallest division is 0.1 cm

$$\Delta = \frac{\text{smallest division}}{2} = \pm 0.05$$

3 Micrometer :- it's smallest division is 0.01 mm

$$\Delta = \frac{\text{smallest division}}{2} = \pm 0.005$$

4 Vernier caliper :- it's smallest division is 0.1 mm

$$\Delta = \frac{\text{smallest division}}{2} = \pm 0.05$$

$$\text{Circumference} \Rightarrow C = \pi d$$

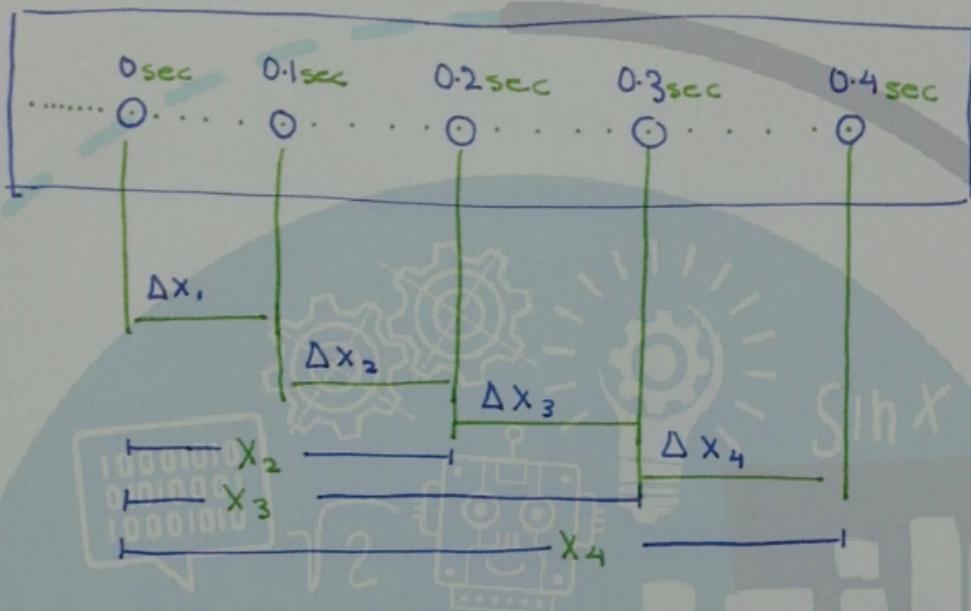
$$\text{volume} \Rightarrow V = \pi \left(\frac{d}{2}\right)^2 h$$

$$\text{density} \Rightarrow \rho = \frac{m}{V} = \frac{m}{\pi \left(\frac{d}{2}\right)^2 h}$$

Experiment 4

Kinematics of rectilinear Motion

* ticker timer :- it makes a dot every 0.02 sec

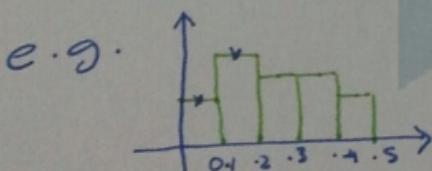


* average velocity $\Rightarrow \frac{\Delta x}{\Delta t} = \bar{v}$
 $\rightarrow 0.1$ constant

* Velocity differences $\Rightarrow \Delta v = v_f - v_i$

* acceleration average $\Rightarrow \bar{a} = \frac{\Delta v}{\Delta t} \rightarrow 0.1$ constant.

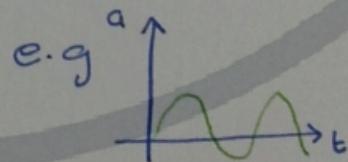
*** note *** the slope of x vs t is the ins. velocity



v increasing ($0.05s - 0.15s$)

v const. ($0.25s - 0.35s$)

v decreasing ($0.15s - 0.25s$)



the displacement

=
area under the curve.

Experiment 11 Specific heat capacity

* specific heat capacity : (it depends on the type of the substance)

- the amount of heat required to raise the temp. of 1 gram of substance by 1°C

its unit is cal/g.C° or J/g.C°

* heat capacity : (it depends on the type and quantity of the substance)

- the amount of heat to raise temp. by 1°C

its unit is J/C° or cal/C°

* heat : the amount of energy gained or lost due to difference in temp.

$$(\text{Q}) \text{heat} = \text{heat Capacity} \times \text{temp. difference.}$$

$$(\text{Q}) \text{heat} = \frac{\text{specific heat capacity}}{\text{mass}} \times \text{temp. difference}$$

$$(\text{Q}) \text{heat} = C \times m \times \Delta T$$

example :- heat gained = heat lost
(calorimeter + water) (metal)

$$\Rightarrow (M_1 C_1 + M_w C_w)(T_f - T_1) = M_2 C_2 (T_2 - T_f)$$

T_1 : temp of water and cup

T_2 : temp of boiling water and metal.

T_f : final temp.

$$\text{let: } X = (M_1 C_1 + M_w C_w)$$

$$C_2 = \frac{XY}{Z M_2}$$

$$Y = \frac{(T_f - T_1)}{\sqrt{b^2 + h^2 - 2bh \cos^2 \alpha}}$$

$$Z = (T_2 - T_f)$$

then,

$$\text{Error in } C_2 \Rightarrow \frac{\Delta C_2}{C_2} = \sqrt{\left(\frac{\Delta X}{X}\right)^2 + \left(\frac{\Delta Y}{Y}\right)^2 + \left(\frac{\Delta Z}{Z}\right)^2 + \left(\frac{\Delta M_2}{M_2}\right)^2}$$

Experiment #3 Vectors

* to calculate the resultant force we have 3 methods:-

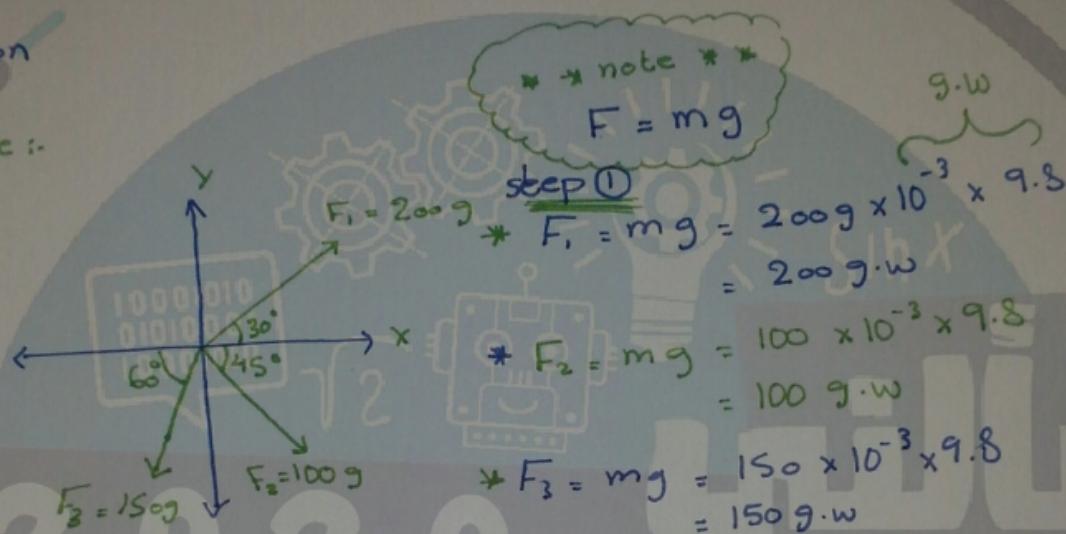
1) Experimental method :- (Force table)

2) Graphical method :-

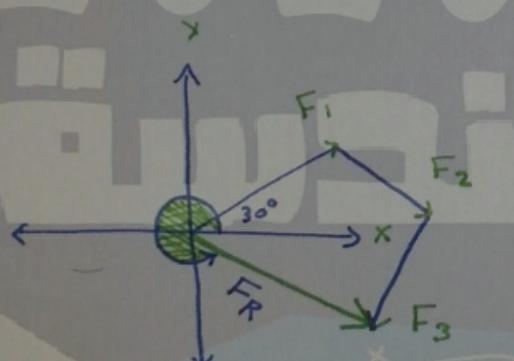
* head to tail

* polygon

example:-



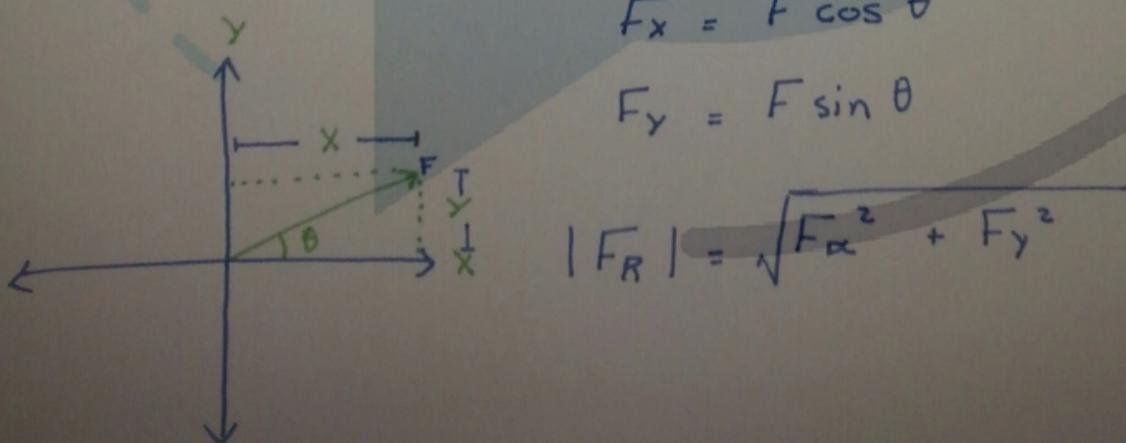
step ②



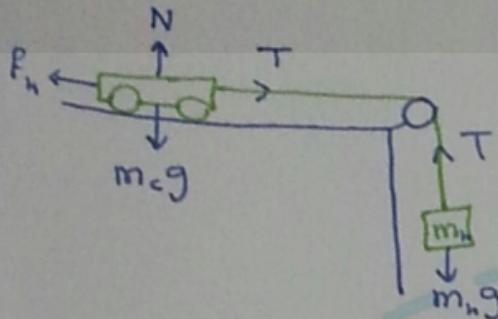
3) Method of components :-

$$F_x = F \cos \theta$$

$$F_y = F \sin \theta$$



Experiment #5 Force and motion.



$$\sum F = m_c a_{\text{tot}}$$

newton 2nd law

$$m_h g - T = m_h a$$

$$T - f_k = m_c a$$

addition

$$m_h g - f_k = (m_h + m_c) a$$

$$m_h g = (m_c + m_h + m_a) a$$

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* * Note * *

$f_k = 0$ when we increase the inclination of the track

example :

* For M_a vs $\frac{1}{a}$

$$m_h g = m_a a + (m_c + m_h) a$$

$$\frac{m_a a}{a} = \frac{m_h g}{a} - \frac{(m_c + m_h) a}{a}$$

$$M_a = m_h g \cdot \frac{1}{a} - (m_c + m_h)$$

$$\text{slope} = m_h g$$

$$-\frac{\sin \theta - \cos^2 \theta}{\sin \theta}$$

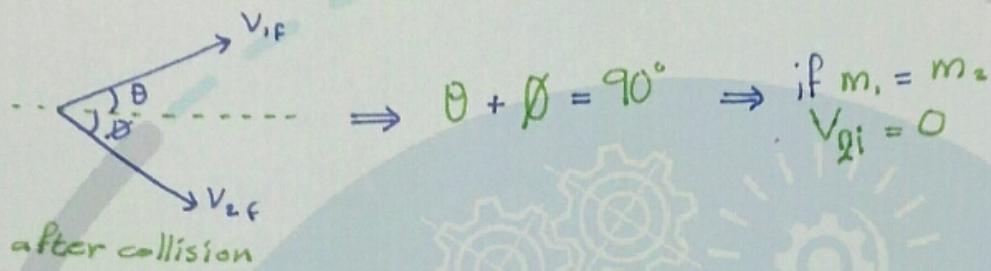
$$y\text{-intercept} = -(m_c + m_h)$$

$$x\text{-intercept} = \frac{(m_c + m_h)}{m_h g}$$

Experiment #6 Collisions in two dimensions

Collisions → head-on collision (1D)
 Collisions → oblique collisions (2D)

* oblique collisions (2D)

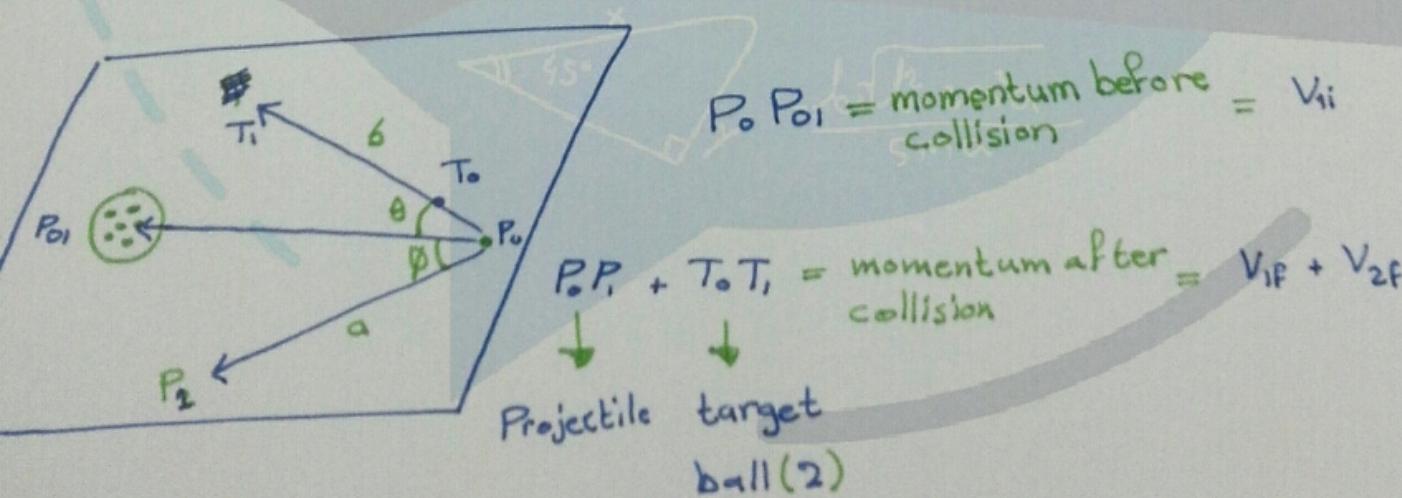


** note **

the type of collision in this experiment is elastic collision.

* momentum conservation :- $\vec{P}_{1i} + \vec{P}_{2i} = \vec{P}_{1f} + \vec{P}_{2f}$
 $m_1 \vec{v}_{1i} + m_2 \vec{v}_{2i} = m_1 \vec{v}_{1f} + m_2 \vec{v}_{2f}$

* elastic collisions :- $KE_i = KE_f$
 $\frac{1}{2} m_1 v_{1i}^2 + \frac{1}{2} m_2 v_{2i}^2 = \frac{1}{2} m_1 v_{1f}^2 + \frac{1}{2} m_2 v_{2f}^2$



Experiment #7 Rotational Motion

[1] $F = ma$

$$mg - T = ma$$

$$T = (g - a)m \rightarrow ①$$

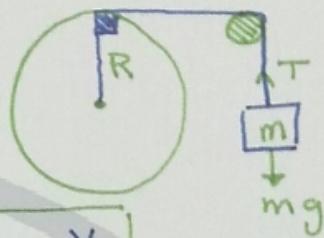
[2] $T = R \times (\vec{F}) = I\alpha$

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Tension

$$\alpha = \frac{a}{R}$$

$$\omega = \frac{v}{R}$$



$$TR = I\alpha \rightarrow ②$$

* From the two equations :-

$$R(g-a)m = I\alpha$$

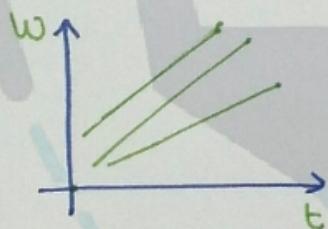
$$Rm(g-\alpha R) = I\alpha$$

$$Rm\left(\frac{g}{\alpha} - R\right) = I$$

moment of Inertia \Rightarrow

* * * note * * * when mass increases, α decreases.

* Plot ω vs t :-



$$\text{slope} = \alpha$$

ω vs t

linear direct relationship

* How to find Torque ?

$$T = I\alpha$$

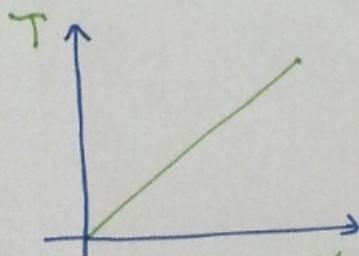
$$[T]_{\text{unit}} = (\text{dyne} \cdot \text{cm})$$

and

$$I\alpha = Rm(g - \alpha R)$$

$$\therefore T = Rm(g - \alpha R)$$

* Plot T vs α



$$\text{slope} = I$$

Experiment #8 Simple harmonic motion

* simple :- no force on it.

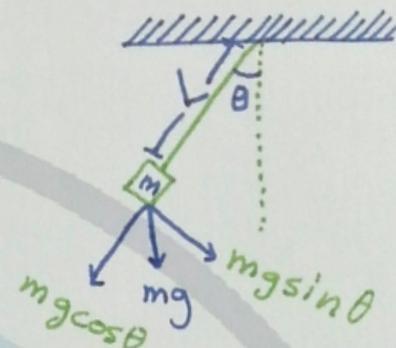
* harmonic :- repeats itself over a certain Period

$$** T = 2\pi \sqrt{\frac{L}{g}} **$$

T: time needed for 1 complete oscillation.

L: length

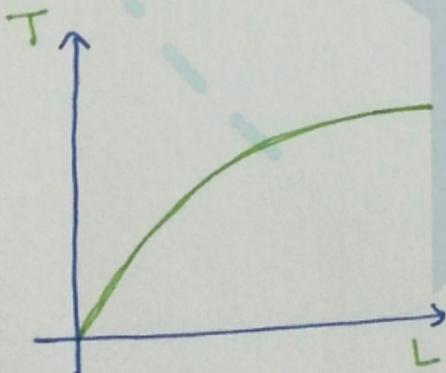
$$* T \propto \sqrt{L} \quad * T \propto \frac{1}{\sqrt{g}}$$



* Plot c. T vs L

$$T = 2\pi \sqrt{\frac{L}{g}}$$

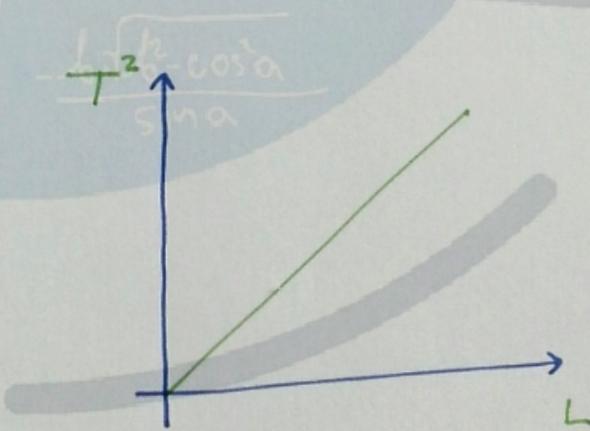
$$T \propto \sqrt{L}$$



* Plot d. T^2 vs L

$$T^2 = \frac{4\pi^2}{g} L$$

$$T^2 \propto L$$

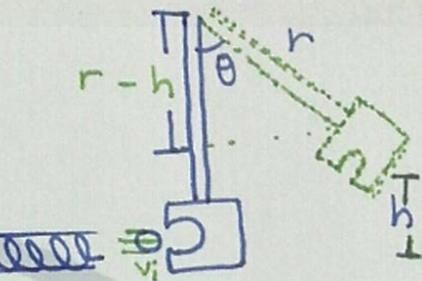


Experiment # 12 Ballistic Pendulum

* $U_i = K_f$ طاقة الاتزان

$$\frac{1}{2} Kx^2 = \frac{1}{2} m_b v_i^2$$

$$v_i = \sqrt{\frac{Kx^2}{m_b}} \rightarrow ①$$



** after the ball is captured by the pendulum.

$$P_i = P_f \quad \text{قبل التصادم} \quad \text{بعد التصادم}$$

$$m_b v_i = (m_b + m_p) v_f \rightarrow ②$$

$$v_f = \left(\frac{m_b}{m_b + m_p} \right) v_i$$

m_b : mass of ball

m_p : mass of pendulum.

$$\cos \theta = \frac{r-h}{r} = 1 - \frac{h}{r}$$

$$h = (1 - \cos \theta) r$$

** at maximum height

$$U_f = K_f$$

$$(m_b + m_p) g \Delta h = \frac{1}{2} (m_b + m_p) v^2$$

$$v_f = \sqrt{2gr(1-\cos\theta)}$$

$$v_i = \left(\frac{m_b + m_p}{m_b} \right) \sqrt{2gr(1-\cos\theta)}$$